



OPERA Experiment, Brick Finding Program

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Dubna, 25th January, 2007

Outline

OPERA experiment
Status of the OPERA detector
BrickFinder program description
Results
Conclusion

OPERA: Oscillation Project with Emulsion tRacking Apparatus





Long baseline experiment

- Direct search for $v_{\mu} \rightarrow v_{\tau}$ oscillations by looking at the appearance of v_{τ} in a pure v_{μ} beam to explain atmospheric neutrinos anomaly and results of K2K and MINOS.
- Search for the sub-dominant $v_{\mu} \rightarrow v_{e}$ oscillations for Θ_{13} measurement

Detection of the v_{τ} appearance signal



Two conflicting requirements:
 Large mass → low Xsection
 High granularity
 → signal selection
 → background rejection

Target: 1800 tons, 5 years running

- 30 000 neutrino interactions
- ~150 v_t interactions
- ~15 v_t identified
- < 1 event of background</p>



The OPERA detector



Target Tracker



Plastic scintillator strips (AMCRYS-H, 6.7m x 2.6cm x 1cm) readout by Kuraray WLS fibres + Hamamatsu PMT's (64 channels)

Target Tracker tasks

- Trigger: ε > 99%
- Brick finding : $\epsilon \approx 70 \div 80\%$
- Initiate muon tagging







Muon spectrometer

 μ identification: ϵ > 95% (TT) $\Delta p/p < 20\%$, p < 50 GeV/c misidentified μ charge prob. < 0.3%





Inner Tracker 11 + 11 planes of RPC's 21 bakelite RPC's (2.9x1.1m²) / plane

muon identification (TT)range measurement

Precision Tracker

6 planes of drift tubes space resolution: ~300μm

o momentum measurement



Lead – Emulsion target

brick (target unit) 56 Pb plates + 57 emulsions



2 emulsion layers (44 µm thick) poured on a 200 µm plastic base

• Micro-metric space resolution (Emulsion) + target mass (Lead)

• Compact and modular structure

Total target mass : 1766 t (206336 bricks, 12 M emulsions and Pb plates)



Brick Manipulator System

Robot for brick insertion (target filling) and removal (during run)



Ventouse Vehicle

Brick





Automatic scanning of nuclear emulsions



Two testing runs

 $\mathbf{\hat{e}}$

August 2006 testing CNGS beam testing Changeable Sheet October 2006 register events in real bricks water leak in a reflector cooling system

There are **28** beam correlated events have been registered during october run



Wall Column Row Prob

1st	brick	-1	-1	-1	0.00
2nd	brick	-1	-1	-1	0.00
3rd	brick	-1	-1	-1	0.00



Wall Column Row Prob

1st bri	ick -1	-1	-1	0.00
2nd bri	ick -1	-1	-1	0.00
3rd bri	ick -1	-1	-1	0.00



Wall Column Row Prob

1st brid	ck −1	-1	-1	0.00
2nd brid	2k −1	-1	-1	0.00
3rd brid	ck −1	-1	-1	0.00



Wall Column Row Prob

1st	brick	-1	-1	-1	0.00
2nd	brick	-1	-1	-1	0.00
3rd	brick	-1	-1	-1	0.00

Brick Finder Program

Brick Finding Program requirements – high efficiency

No new bricks will be inserted (to save the effective mass of target)

~30 Bricks per day (5 years of data taking)

Cleaning Event

Cellular Automation





Reconstruction muon track direction Hough Method Kalman Filter Tracing Method



Reconstruction Hadron Jet direction

Reweighting hits method





Define wall with interaction

Neural Network





Find Brick



Define most probable brick



Results (v_{μ} CC events) "1 of 3" Full detector Wall reconstruction efficiency: 1 wall 0.85 0.94 Brick finding efficiency 0.70 1 brick 0.71 2 bricks 0.87 0.85 0.91 3 bricks 0.92

Improvements

 Hits coordinate correction after TT modules alignment with the help of muon tracks (S. Zemskova analysis)

 Daily bricks map is used for the precise predictions



	Wall	Column	Row	Prob
1st brick	27	45	7	0.52
2nd brick	27	45	8	0.48
3rd brick	27	46	7	0.00



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3rd	brick	27	46	7	0.00

Conclusion

- Developed BF program (91%) efficiency)
- Daily bricks map is used for the precise predictions
- Implementation of TT alignment will be come in future